

Numerical and experimental study of debris flow

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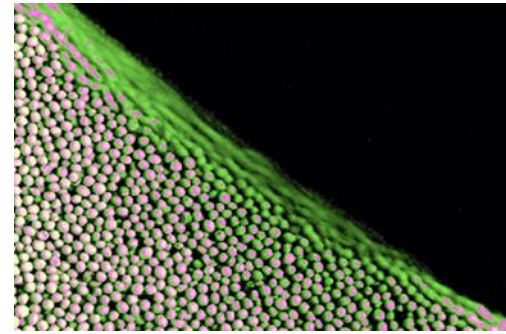
Landslides and debris flows



Content

- Constitutive model: solid and fluid
- SPH: numerical model for large deformation
- LBM-DEM: model for debris flow
- Outlook

Granular flow: from slow to fast



- Stress decomposition (static part+dynamic part):

$$\boldsymbol{\sigma} = \boldsymbol{\sigma}_h + \boldsymbol{\sigma}_d \quad \dot{\boldsymbol{\sigma}} = \dot{\boldsymbol{\sigma}}_h + \dot{\boldsymbol{\sigma}}_d$$

- Static part:

$$\dot{\boldsymbol{\sigma}}_h = \mathbf{L}(\boldsymbol{\sigma}, \dot{\boldsymbol{\epsilon}}) + f(e)\mathbf{N}(\boldsymbol{\sigma})\|\dot{\boldsymbol{\epsilon}}\|$$

- Dynamic part:

$$\dot{\boldsymbol{\sigma}}_d = \mathbf{H}(\boldsymbol{\sigma}, \dot{\boldsymbol{\epsilon}}, \ddot{\boldsymbol{\epsilon}}, e)$$

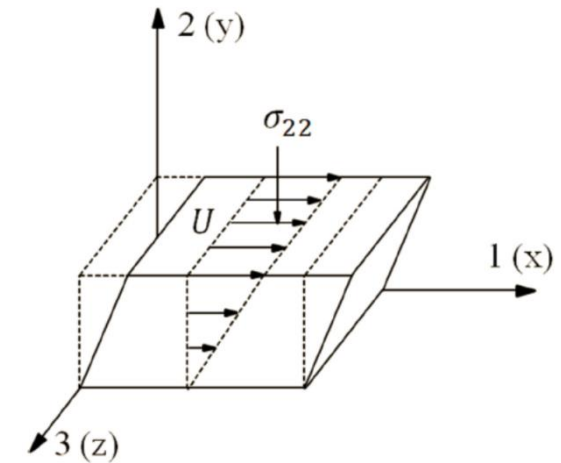
- Some remarks

Bagnold's findings:

- Macro viscous regime:

$$T_v = k_1 \frac{dU}{dy},$$

$$k_1 = 2.25 \lambda^{\frac{3}{2}} \mu,$$



- Grain inertia regime:

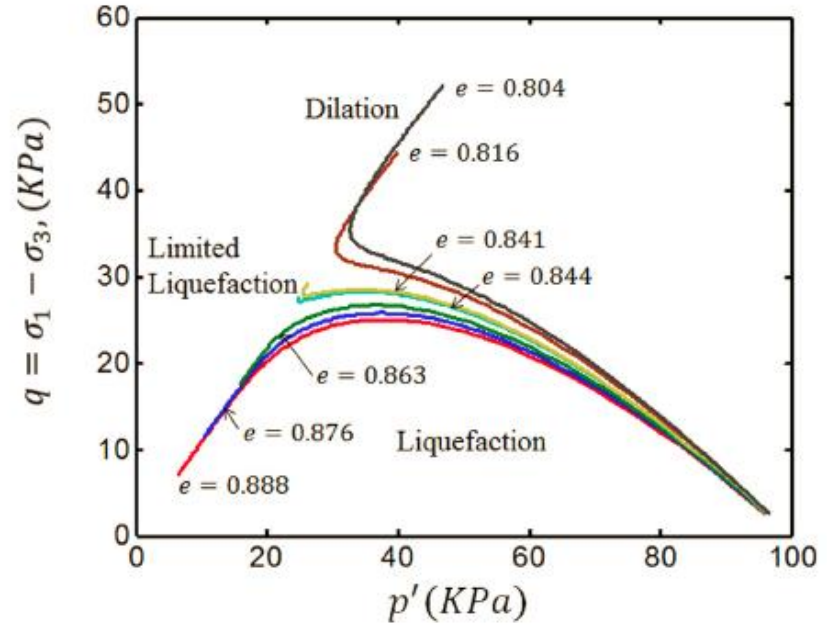
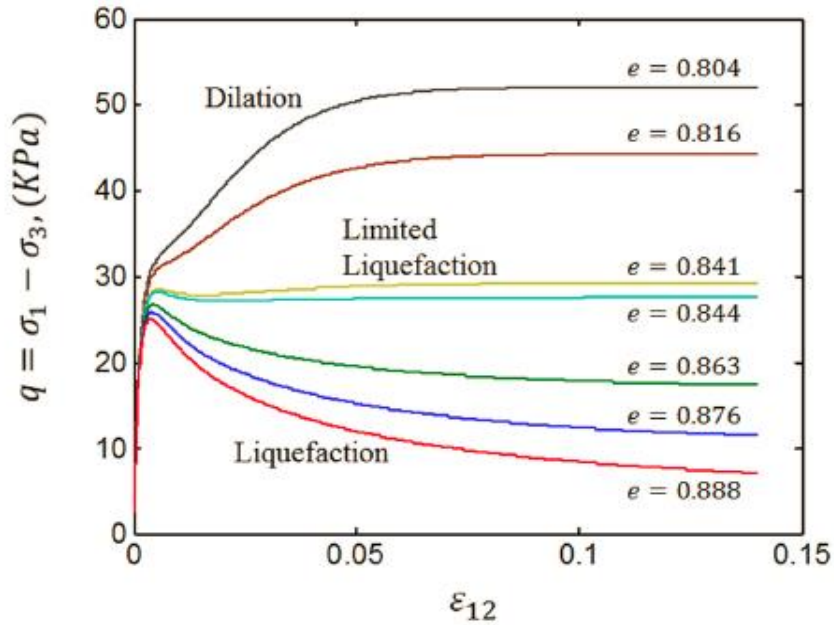
$$T_i = k_2 \left(\frac{dU}{dy} \right)^2,$$

$$k_2 = 0.042 \rho_s (\lambda d)^2 \sin \alpha_i,$$

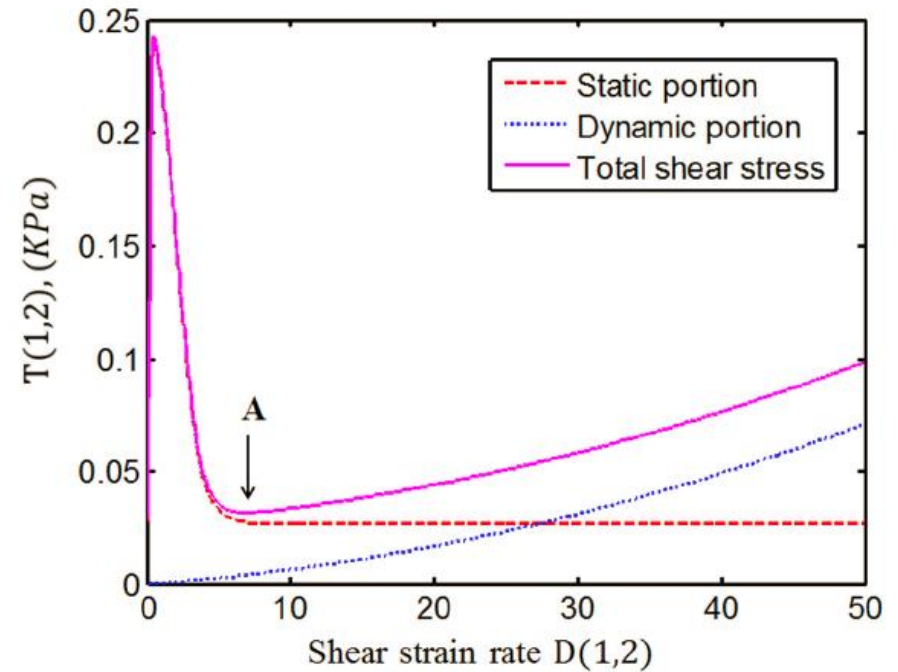
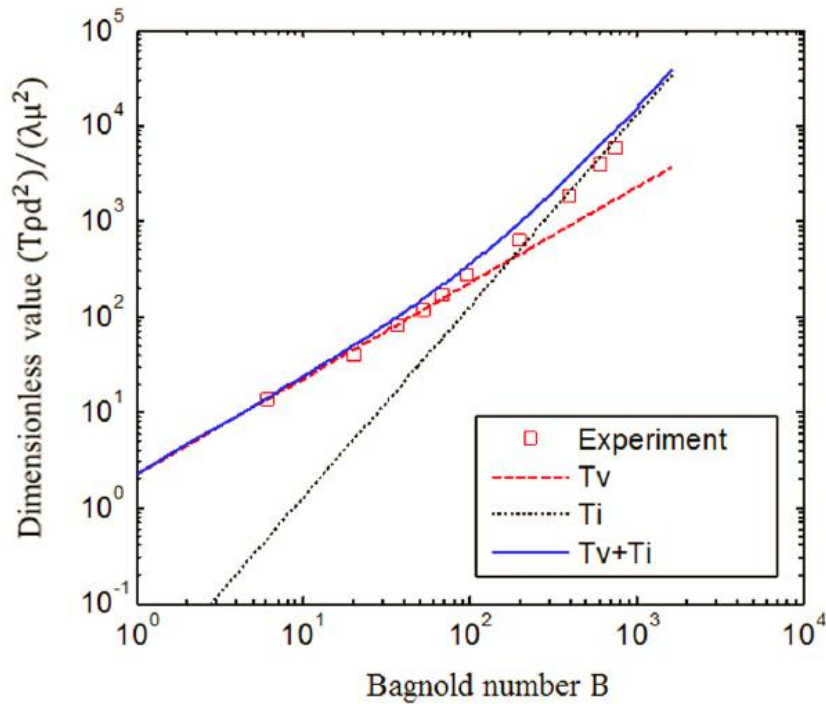
- Bagnold number:

$$B = \frac{\lambda^{\frac{1}{2}} \rho_s d^2 (dU/dy)}{\mu},$$

Model performance (SS)

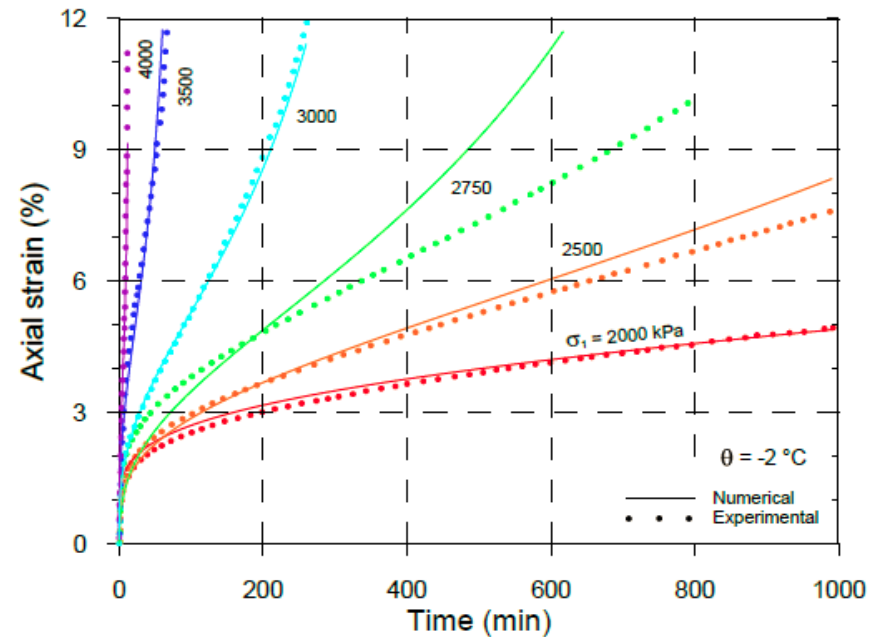
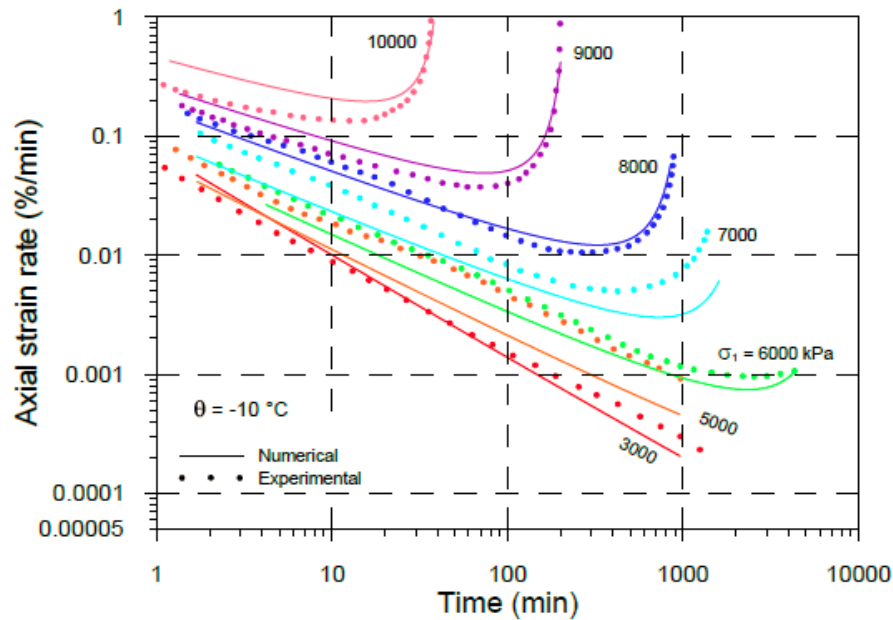


Numerical simulation of simple shear

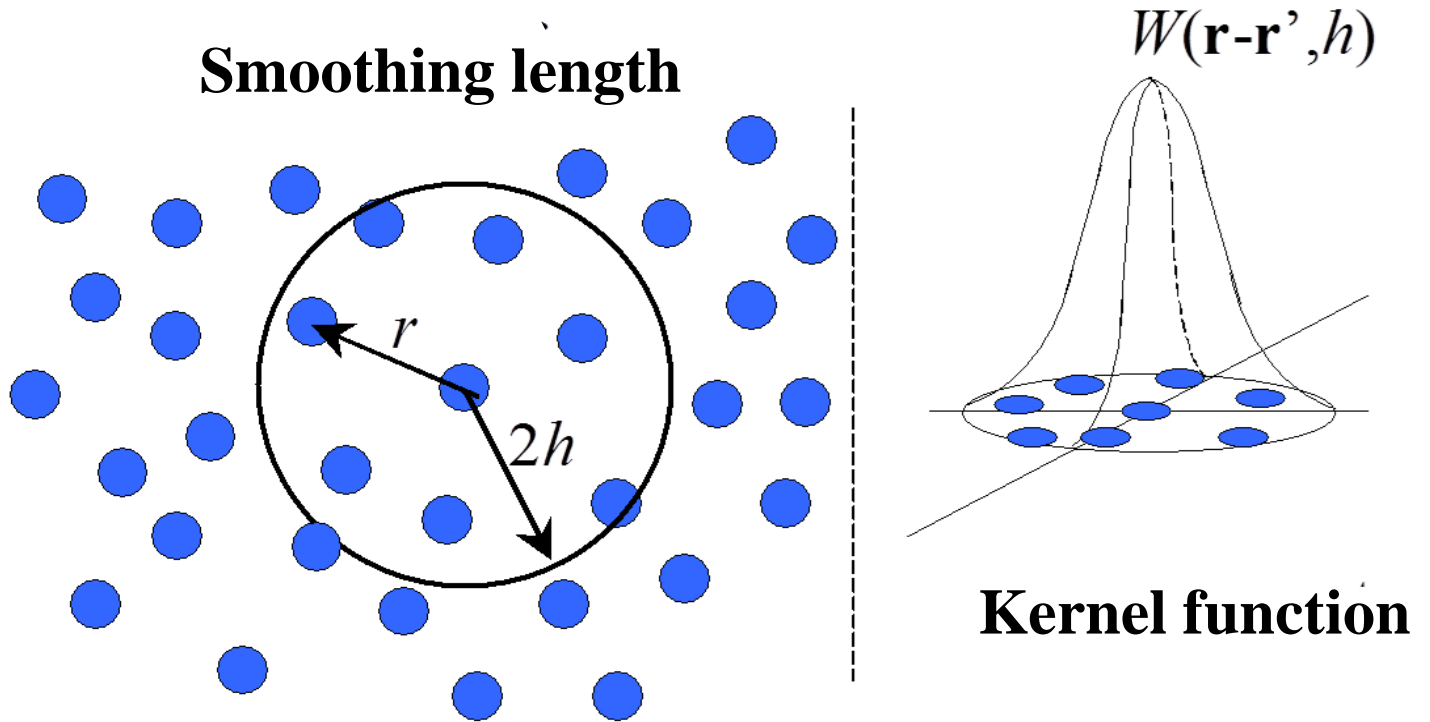


Modelling creep

$$\dot{\mathbf{T}} = \dot{\mathbf{T}}_h + \dot{\mathbf{T}}_d = \mathbf{0}$$



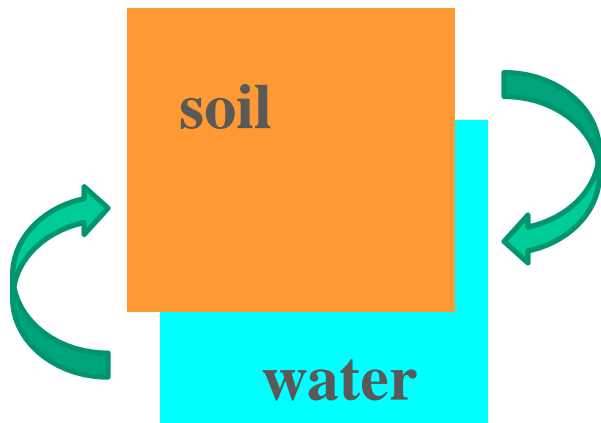
SPH Principle



Field equations: Soil-water mixture

Mathematical model – Mixture theory

- Soil and water occupy the whole domain simultaneously;
- Each constituent satisfies its own balance equations;
- Interactions are modelled by buoyance force and drag force.



$$\partial_t(\tilde{\rho}_s \phi_s) + \nabla \cdot (\tilde{\rho}_s \phi_s \mathbf{v}_s) = 0$$

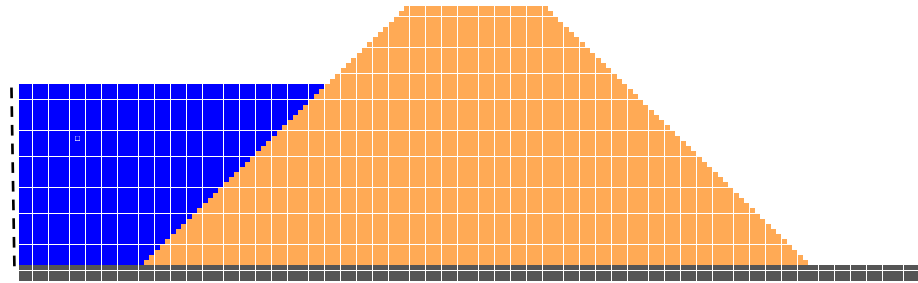
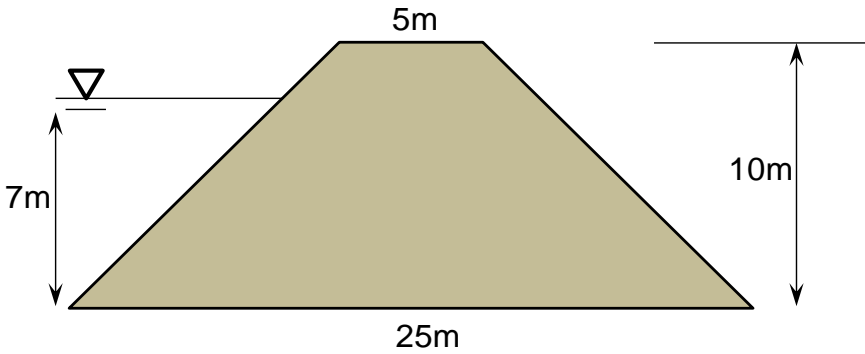
$$\begin{aligned} \partial_t(\tilde{\rho}_s \phi_s \mathbf{v}_s) + \nabla \cdot (\tilde{\rho}_s \phi_s \mathbf{v}_s \mathbf{v}_s) \\ = \nabla \cdot (\phi_s \boldsymbol{\sigma}_s) + \tilde{\rho}_s \phi_s \mathbf{g} - \phi_s \nabla p + \mathbf{f}_d \end{aligned}$$

$$\partial_t(\tilde{\rho}_f \phi_f) + \nabla \cdot (\tilde{\rho}_f \phi_f \mathbf{v}_f) = 0$$

$$\begin{aligned} \partial_t(\tilde{\rho}_f \phi_f \mathbf{v}_f) + \nabla \cdot (\tilde{\rho}_f \phi_f \mathbf{v}_f \mathbf{v}_f) \\ = -\phi_f \nabla p + \nabla \cdot (\phi_f \boldsymbol{\tau}_f) + \tilde{\rho}_f \phi_f \mathbf{g} - \mathbf{f}_d \end{aligned}$$

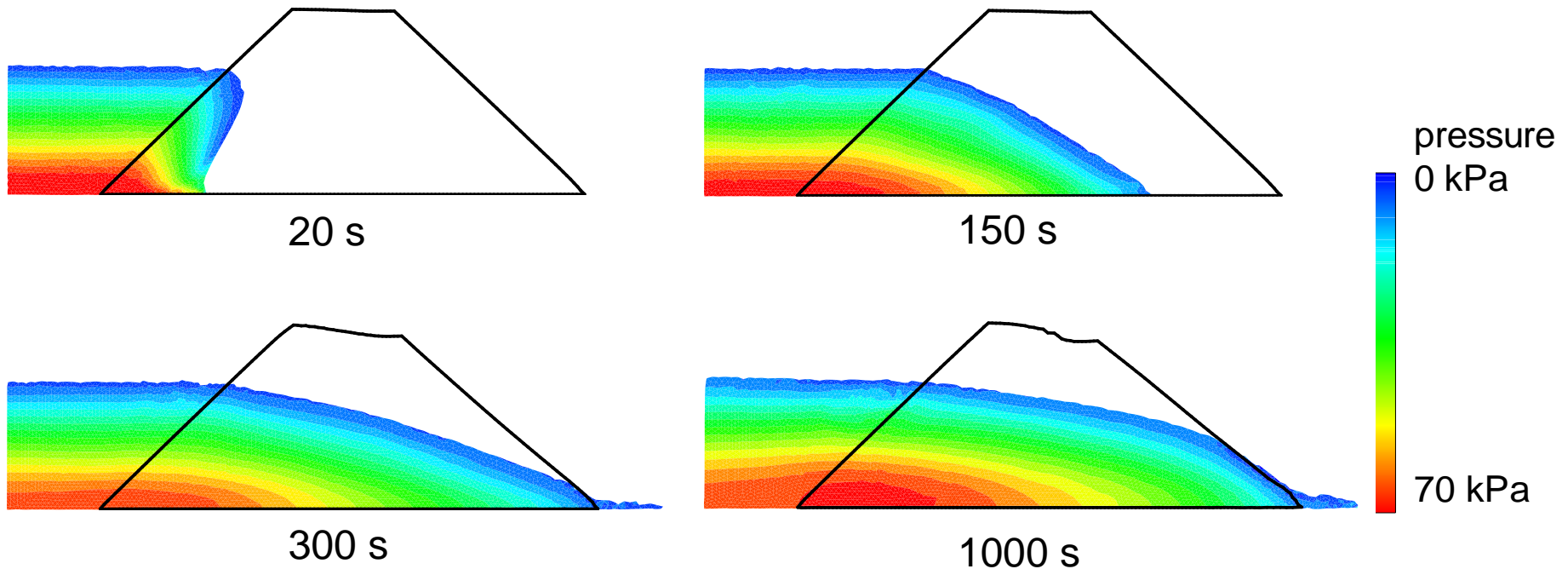
Numerical example

Seepage failure of an embankment



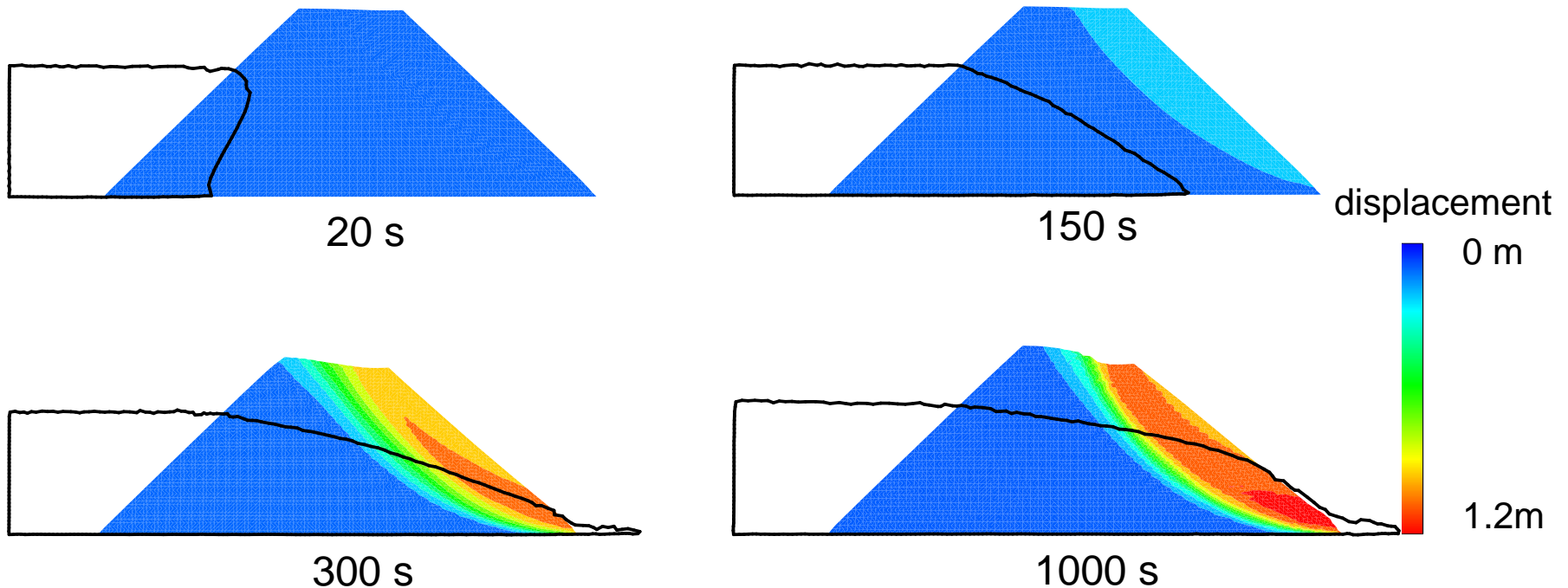
Numerical example

Problem 2: Seepage failure of an embankment



Numerical examples

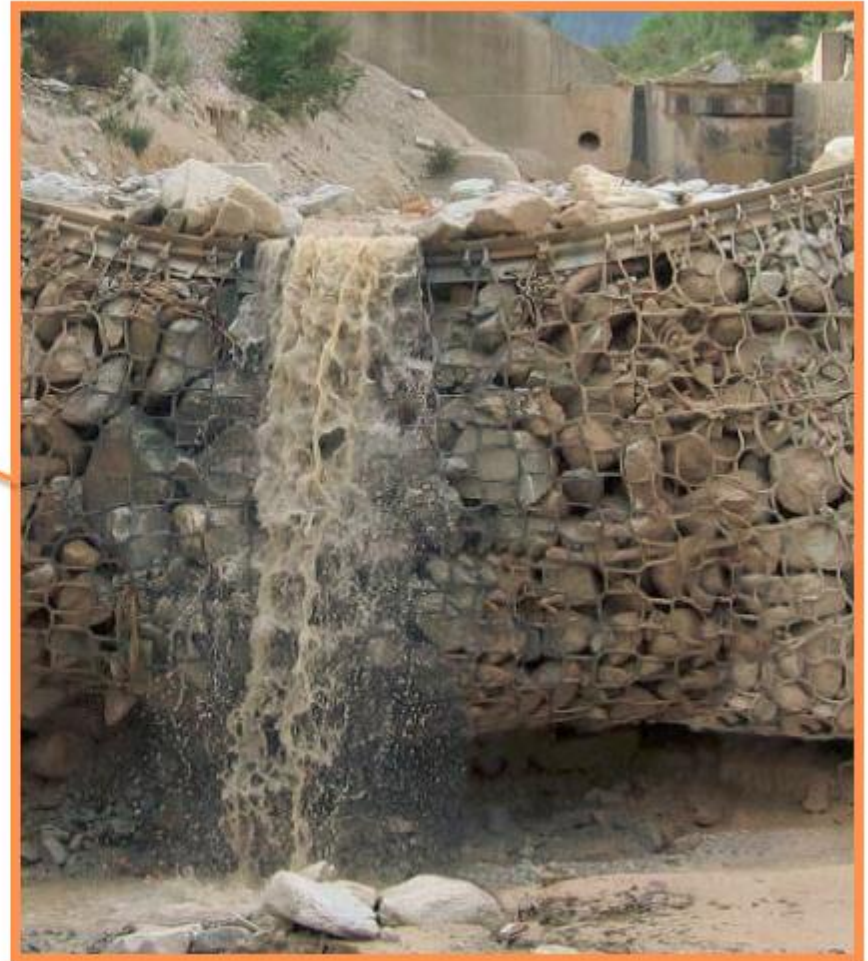
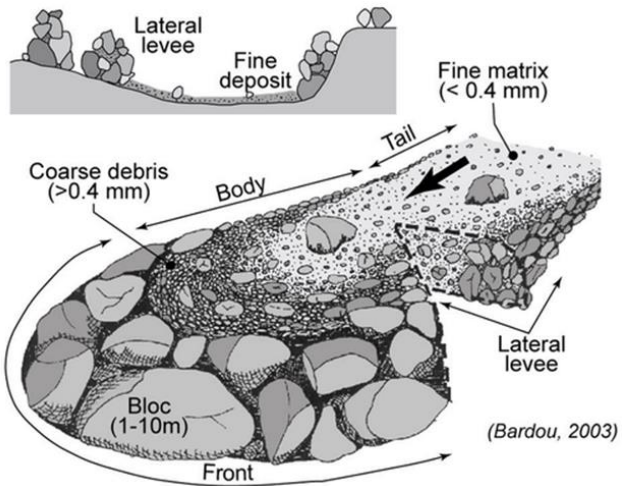
Seepage failure of an embankment



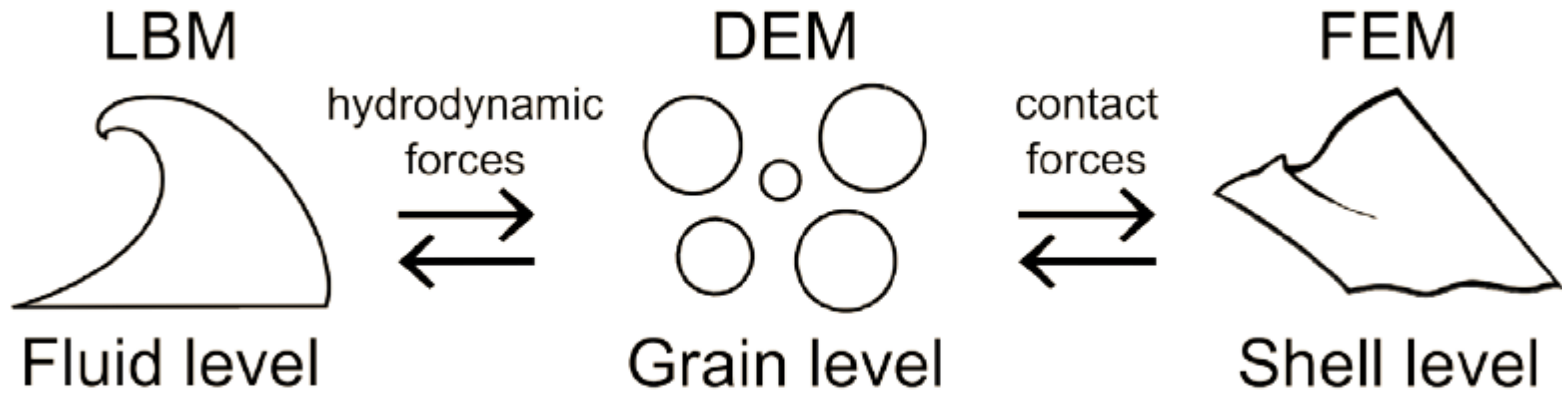
LBM-DEM-FEM




Images of the test conducted by Geobrugg AG



Why these methods?

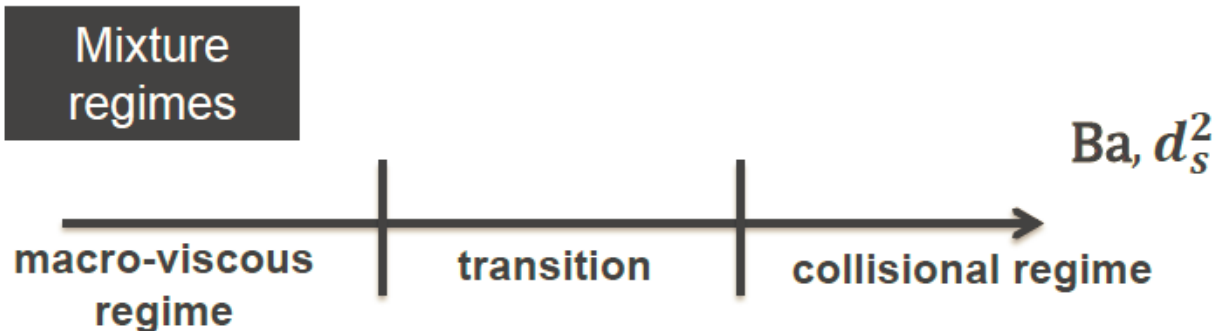


Rheology of debris material

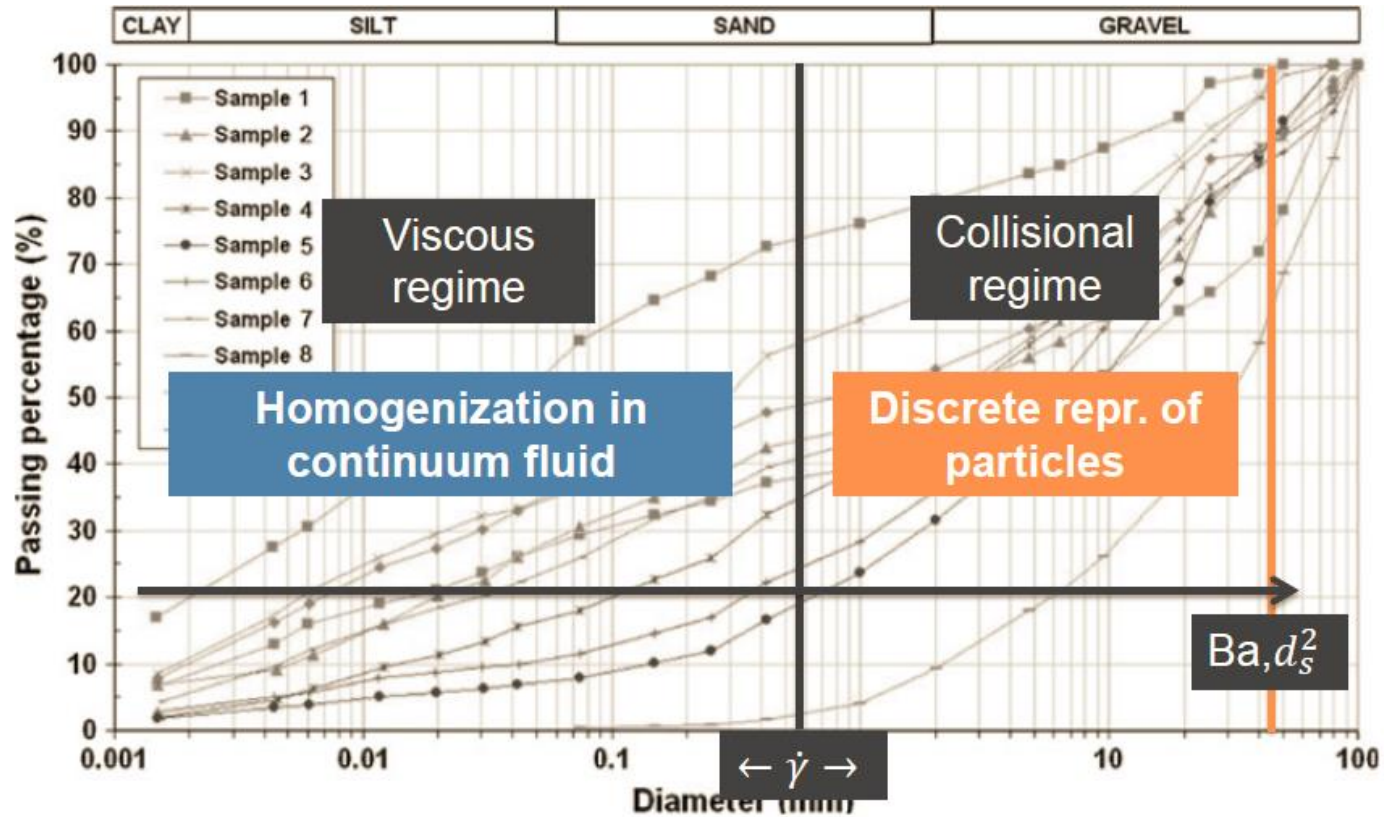

$$\frac{\sigma_{coll}}{\sigma_{visc}} = \frac{\rho_s d_s^2 \lambda_s^{1/2} \dot{\gamma}}{\mu_f} = \text{Ba}$$

Bagnold Number

- ρ_s particle density
- d_s particle size
- λ_s particle concentration
- $\dot{\gamma}$ shear rate
- μ_f fluid dynamic viscosity

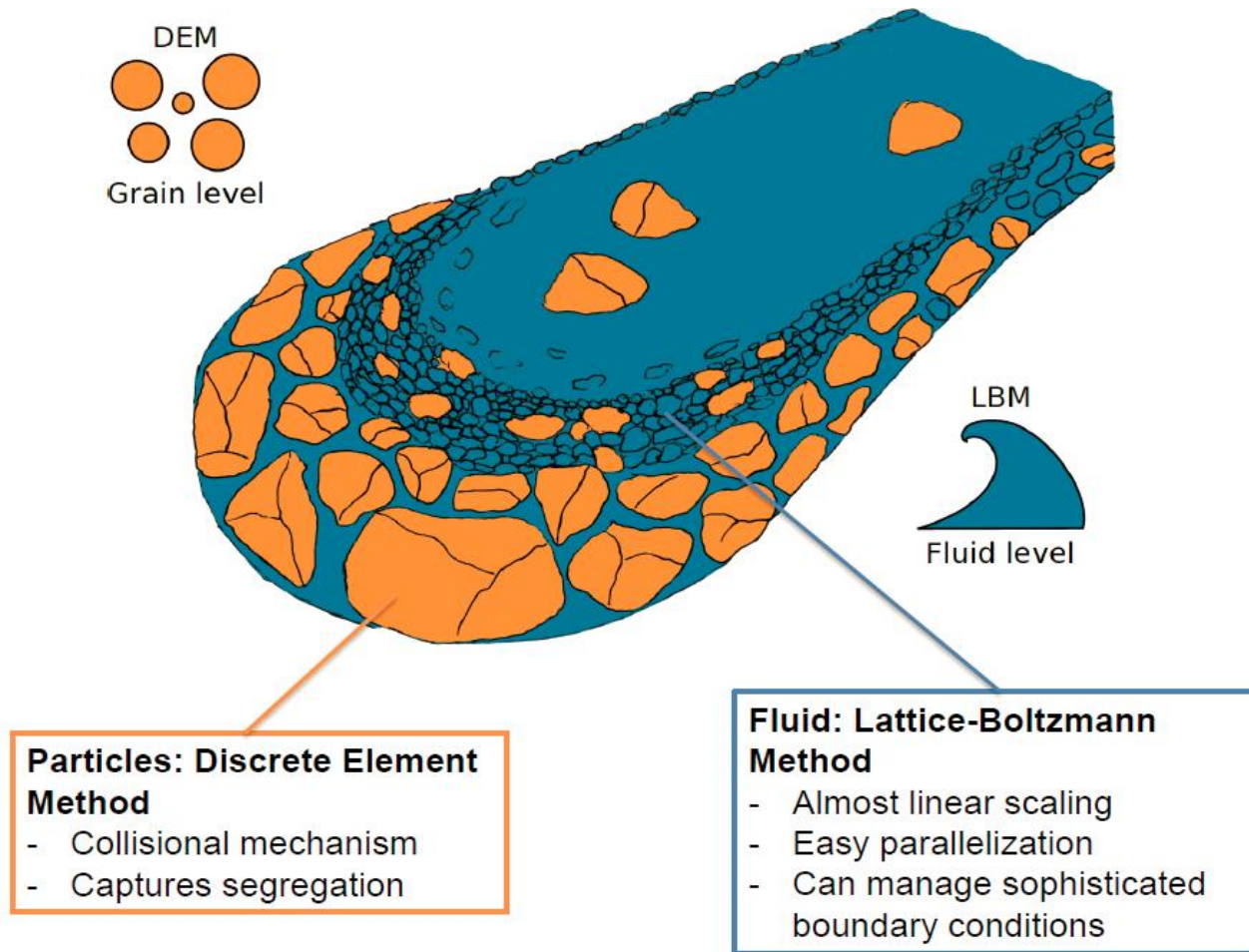


Fluid and solid



T. Bisantino, P. Fischer & F. Gentile, "Rheological characteristics of debris-flow material in South-Gargano watersheds", *Natural Hazards*, 54(2), 209-223, 2009

LBM-DEM coupling

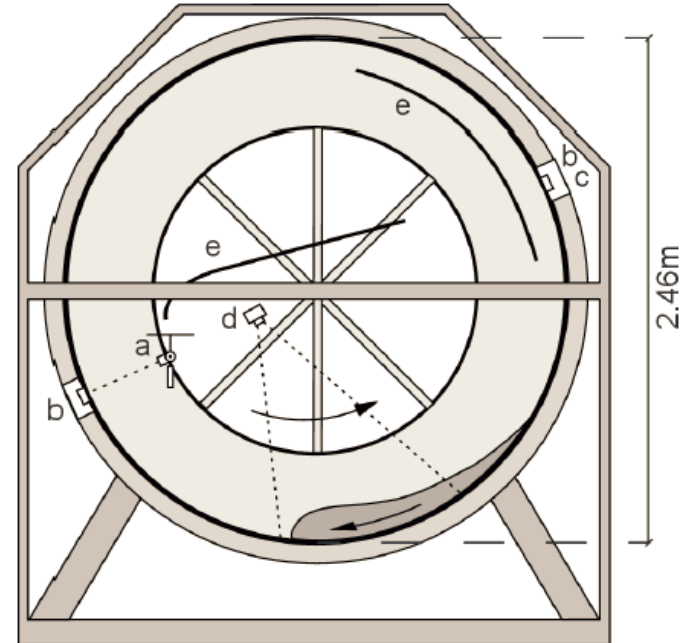


Debris material: viscosity measurement

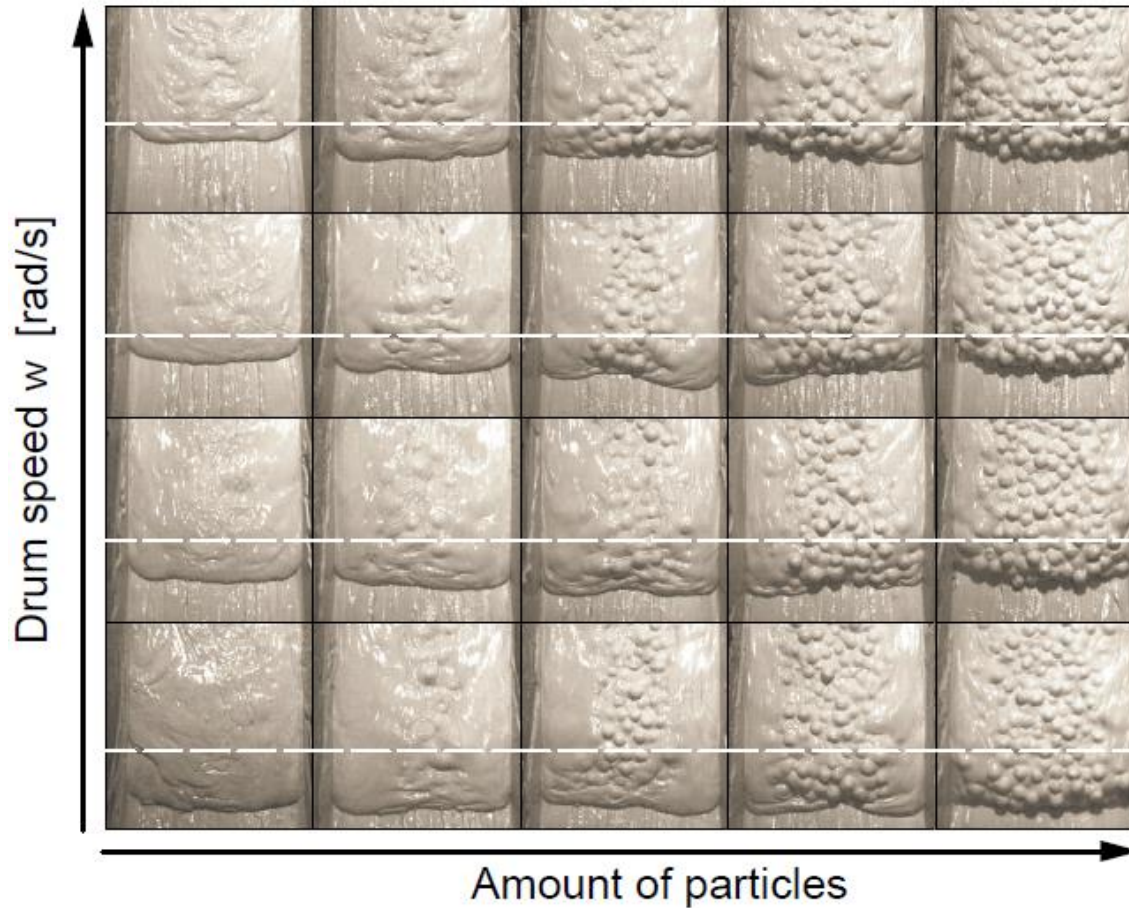
Conventional



Rotating drum (cylinder)

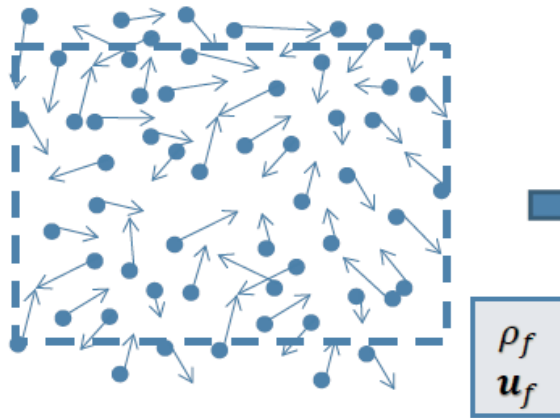


Flow pattern (clay balls in kaolinite suspension)



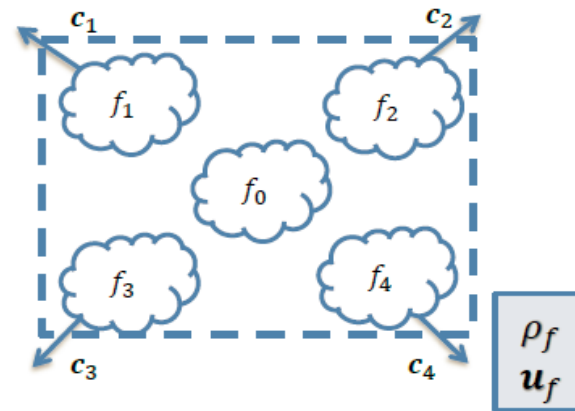
LBM basics

A mesoscopic approach to fluid dynamics



Probability density function «Population»

$$f = f(\mathbf{x}, t, \mathbf{c}) \quad \text{cloud } f_i \rightarrow \mathbf{c}_i$$

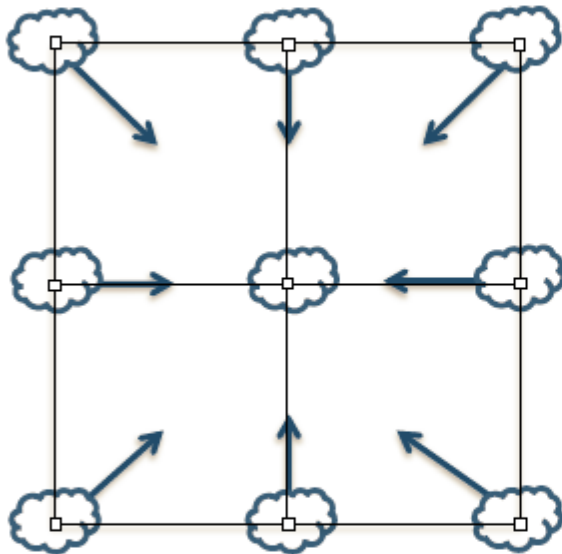


Density $\rho_f = \sum_i f_i$

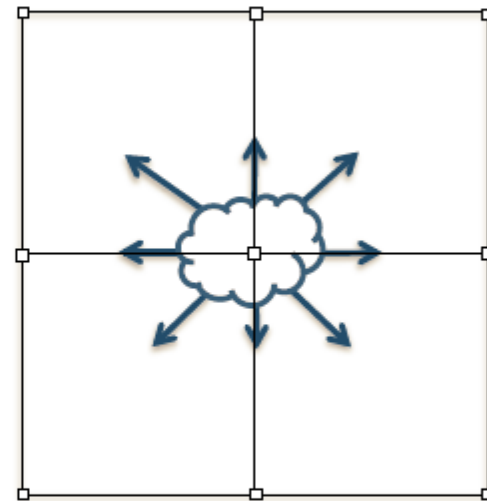
Velocity $\mathbf{u}_f = \sum_i f_i \mathbf{c}_i / \rho_f$

A two-step solution procedure:

Streaming Step



Collision Step



$$\underbrace{f_i(\mathbf{x} + \mathbf{c}_i, t + 1)}_{\text{Streaming}} = \underbrace{f_i(\mathbf{x}, t)}_{\text{Collision}} + \underbrace{\Omega_i(\mathbf{x}, t)}_{\text{Collision}}$$

Rotating drum test

Mixture (40% particles), rotating drum with variable angular speed



0.3 rad/s



0.7 rad/s



0.9 rad/s

Numerical simulation

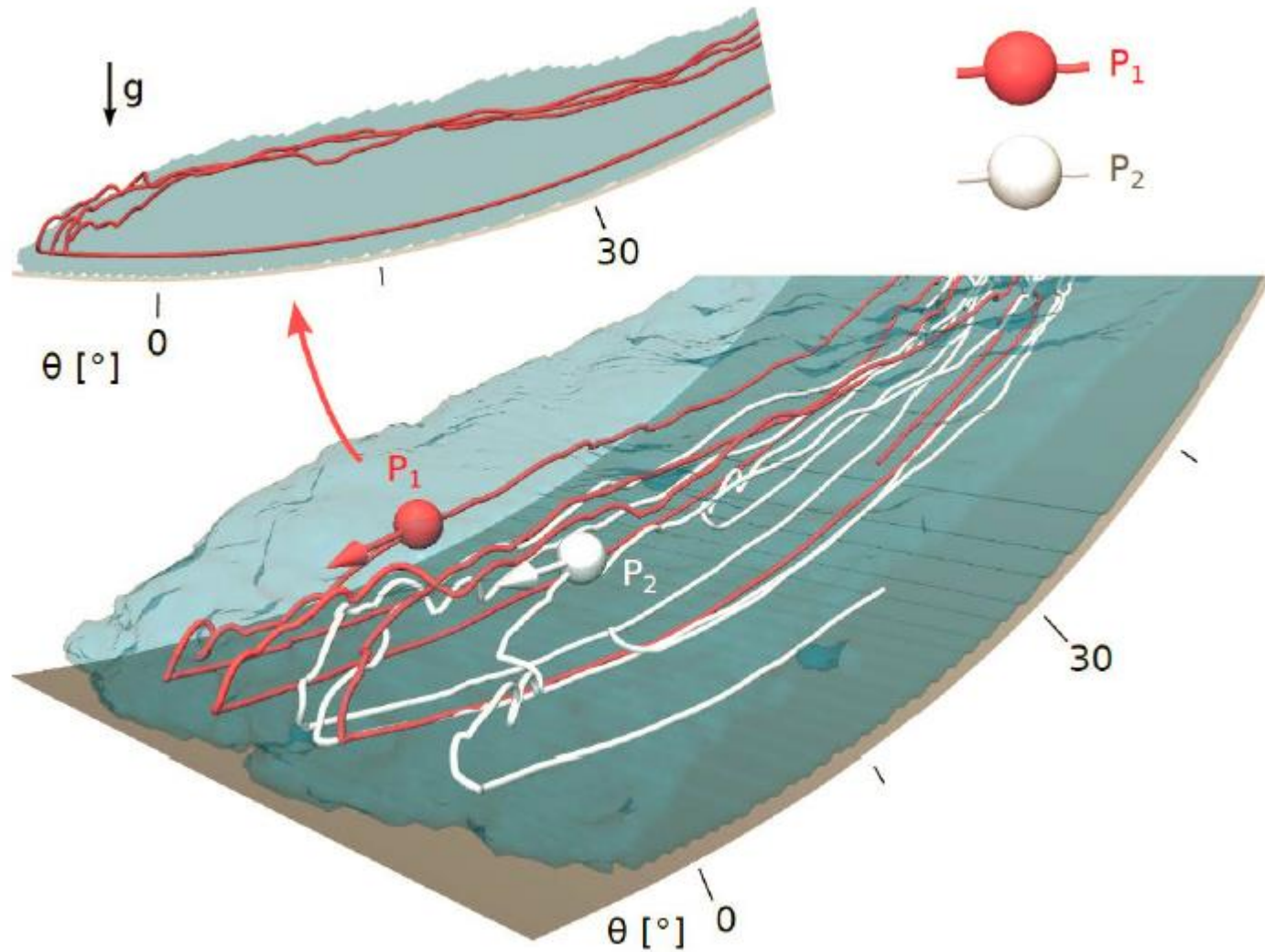
Mixture (40% particles)



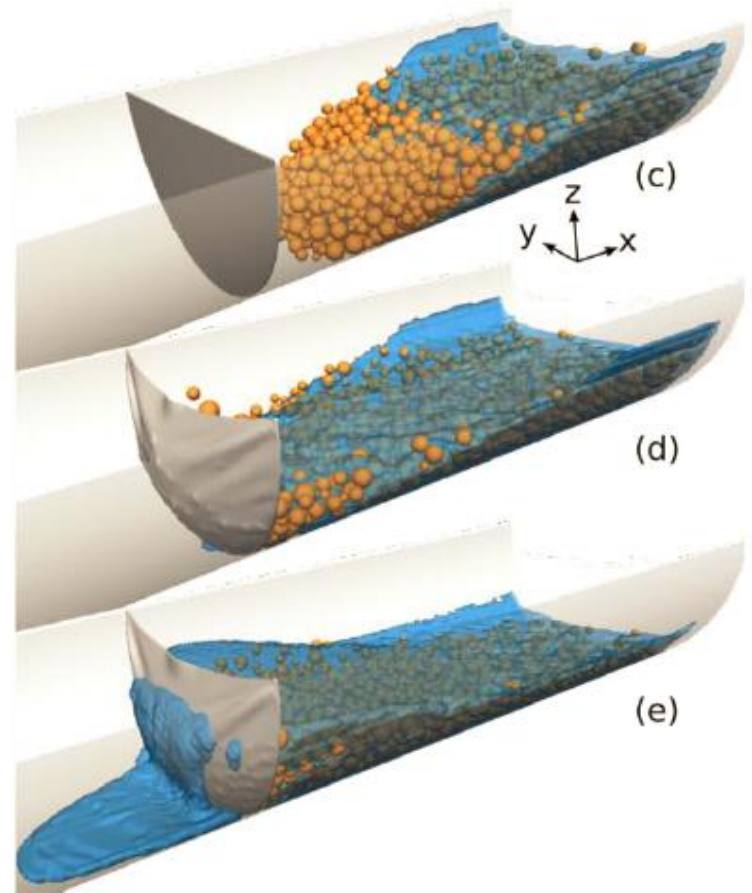
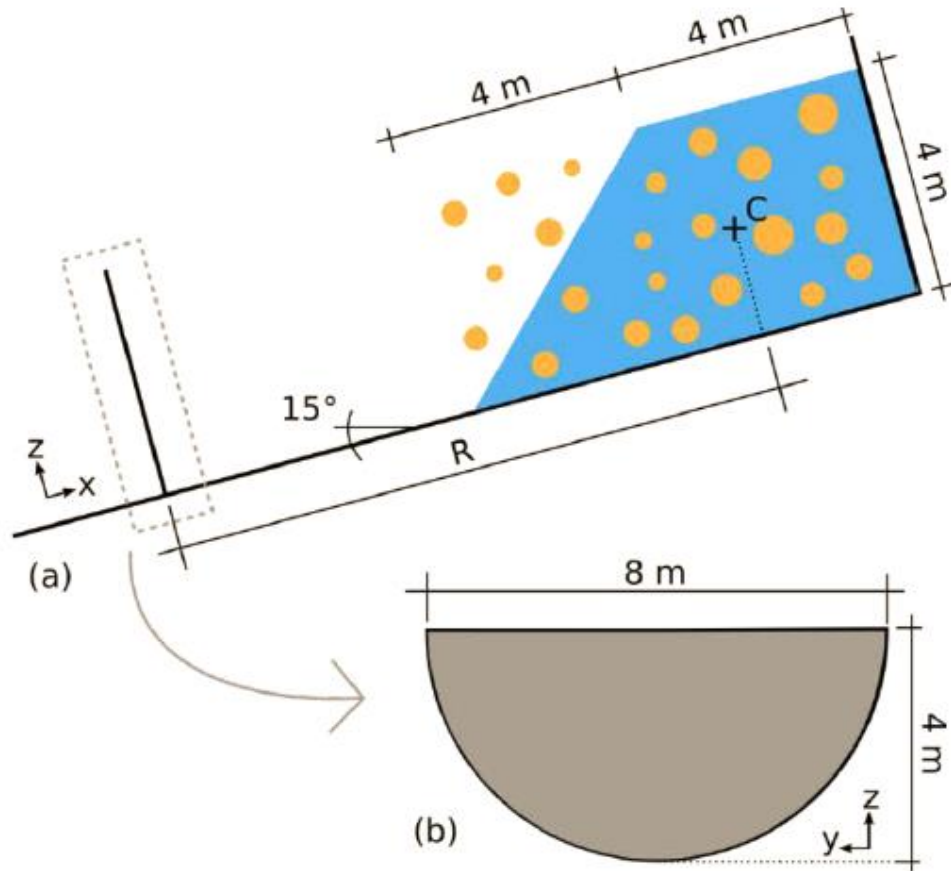
0.3 rad/s

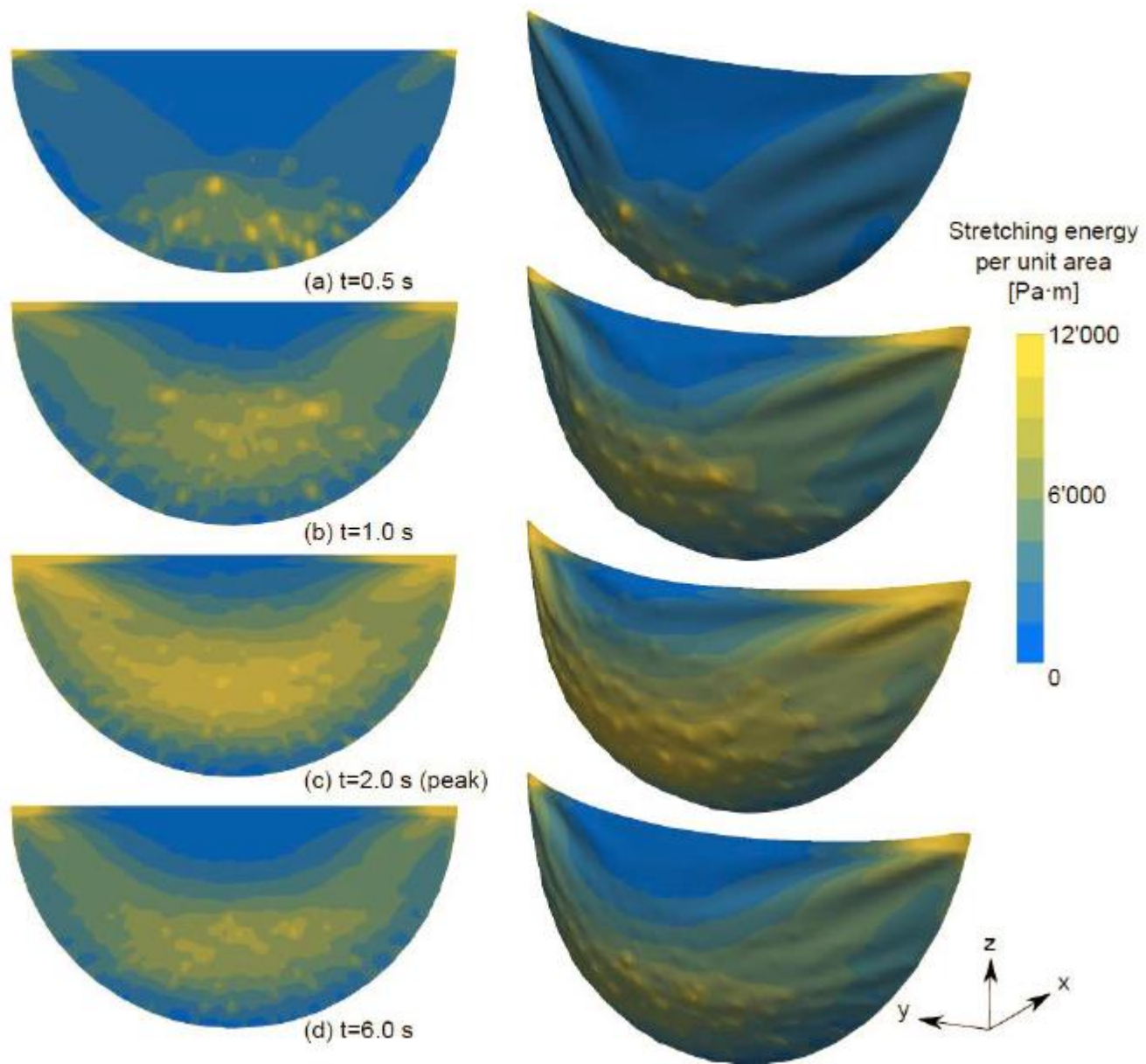


0.9 rad/s

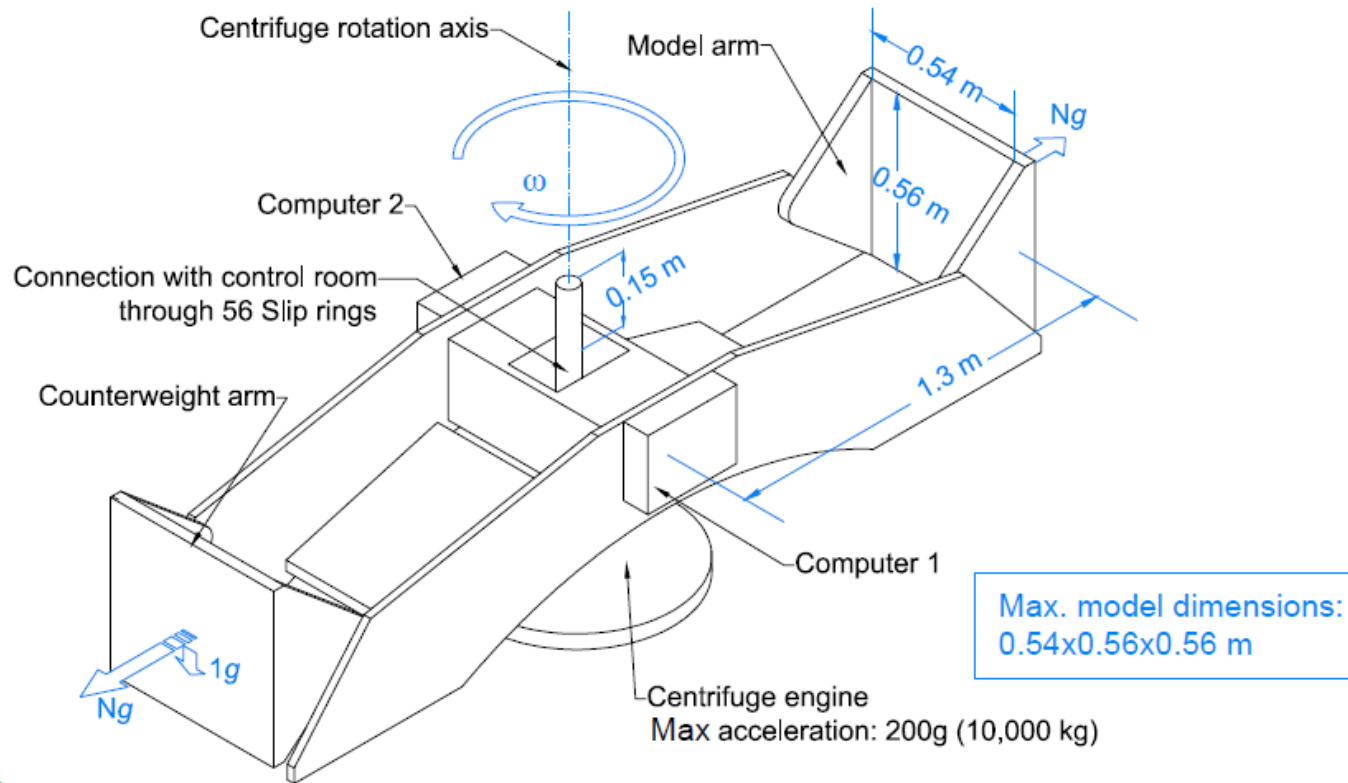


LBM-DEM-FEM: flexible barrier

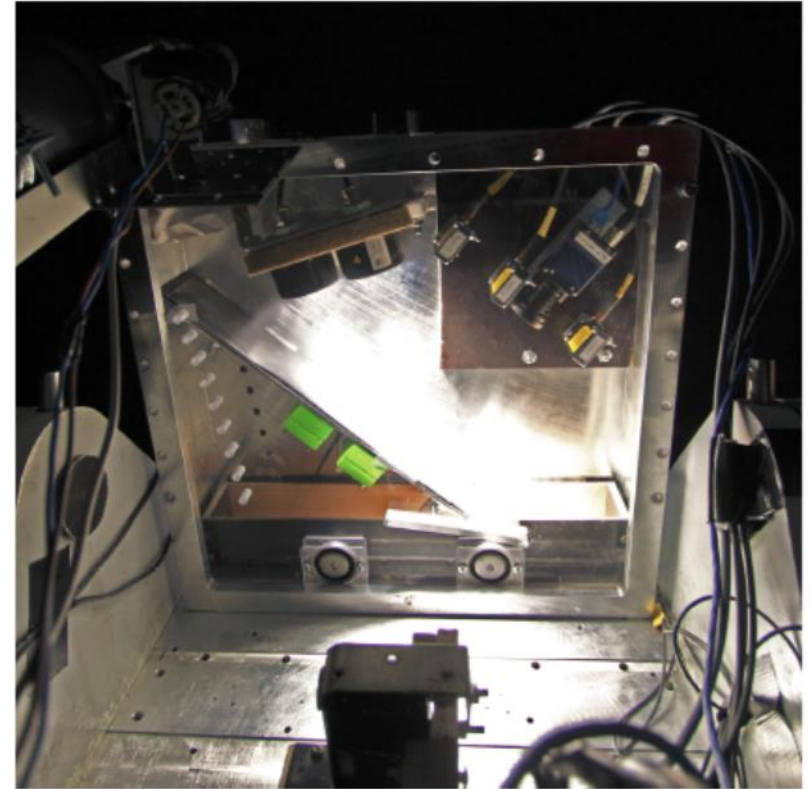
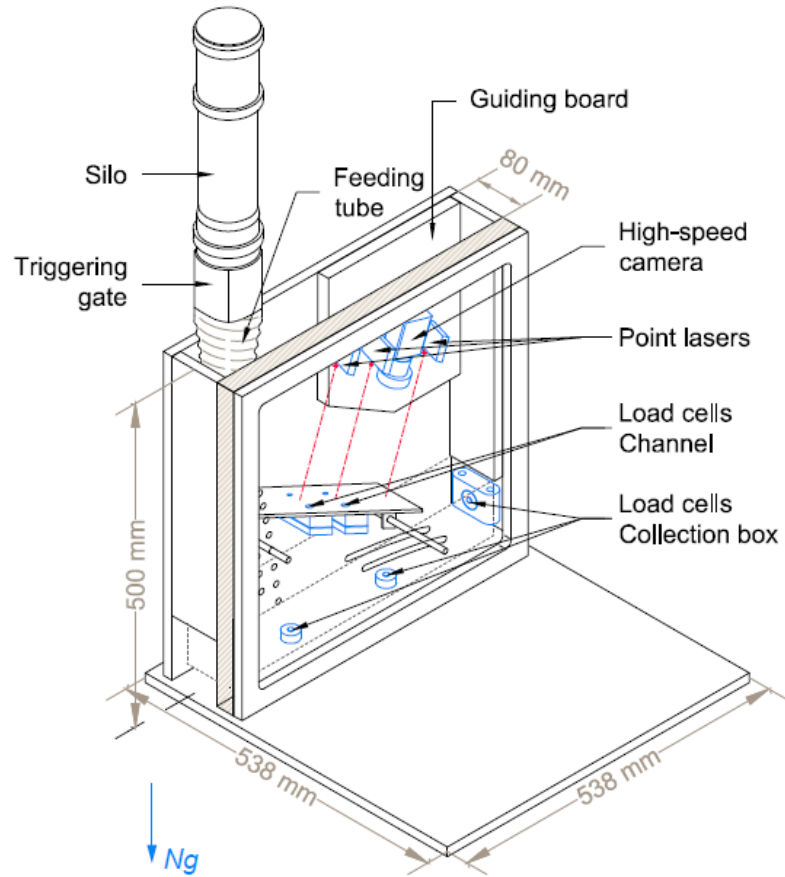


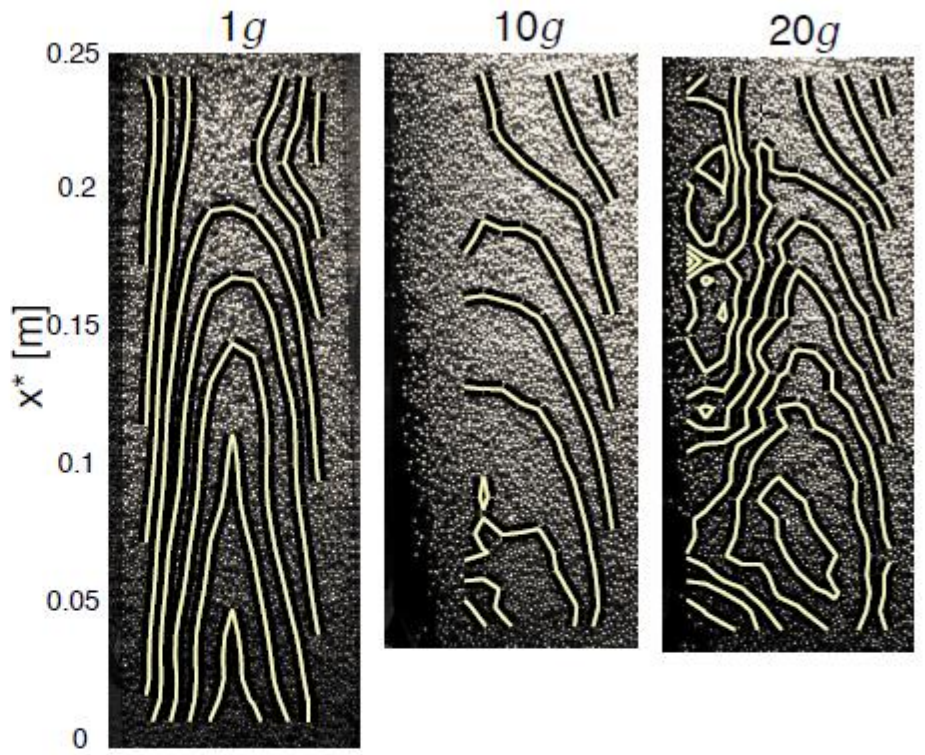
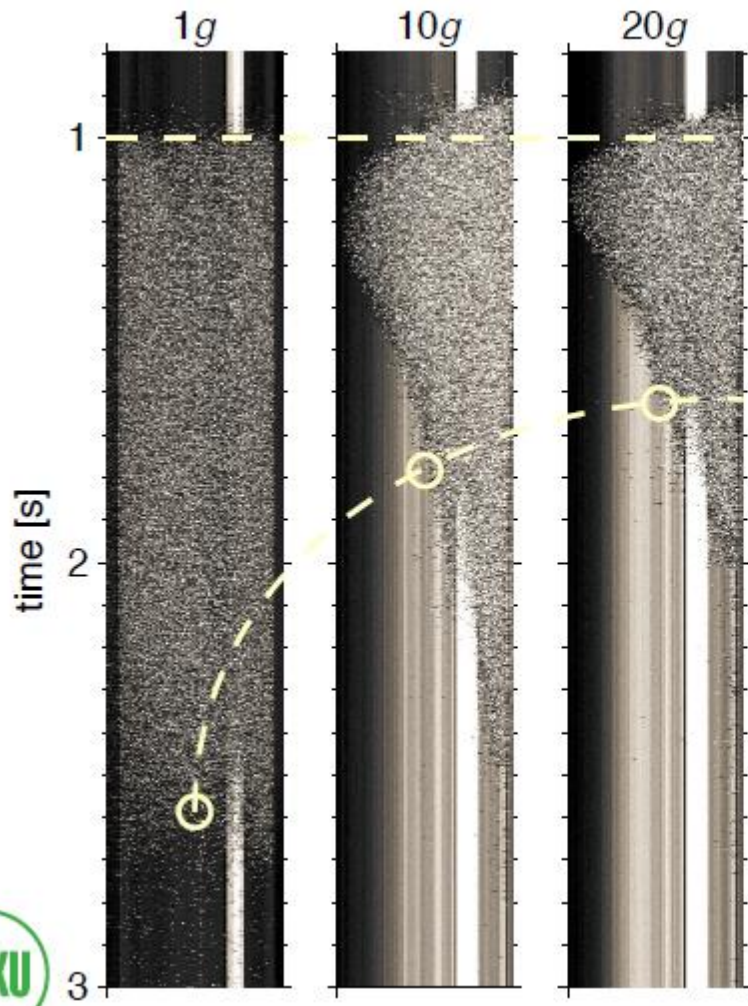


Centrifuge in Vienna

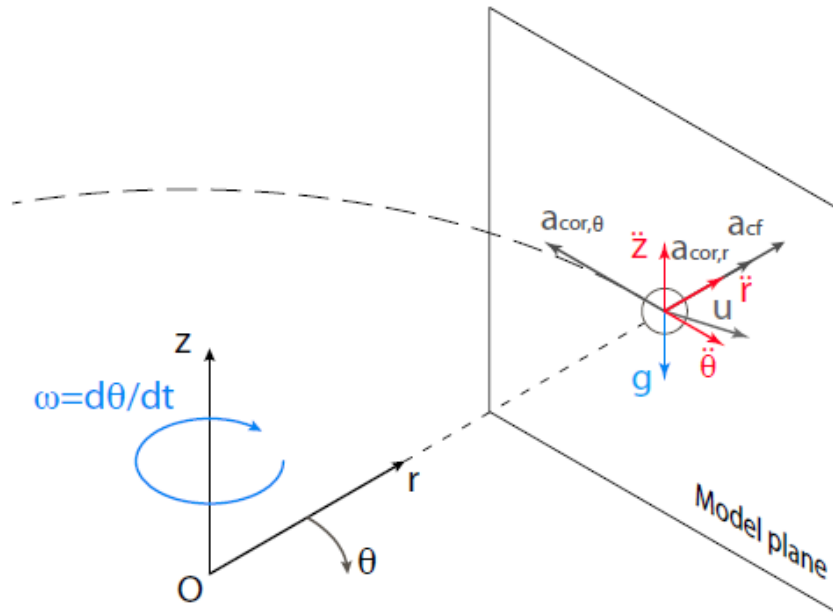


Model box





Centrifuge and Coriolis force



- Centrifugal acceleration:
 $\mathbf{a}_{cf} = r\omega^2\hat{r} \equiv Ng$
- Coriolis acceleration:
 $\mathbf{a}_{cor} = -(2\dot{\mathbf{r}} \times \boldsymbol{\omega})\hat{\theta} + (2\dot{\theta} \times \boldsymbol{\omega})\hat{r}$
- Net-inertial acceleration:
 $\mathbf{a}_0 = \ddot{\mathbf{r}}\hat{r} + \ddot{\theta}\hat{\theta} + \ddot{\mathbf{z}}\hat{z} - g\hat{z}$

7th Framework of European Commission

MUltiscale **M**Odeling of **L**Andslides and **D**Ebris flows

MUMOLADE

Ch. Peng, A. Leonardi, M. Cabrera, F. Wittel, H.J. Herrmann